



# Résolution de problèmes black-box avec LocalSolver

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**Innovation 24 & LocalSolver**

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# Who we are



Bouygues, one of the French largest corporation, €33 bn in revenues  
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**Innovation24**

Operations Research subsidiary of Bouygues  
20 years of practice and research  
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**LocalSolver**

Mathematical optimization solver  
commercialized by Innovation 24  
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# LocalSolver

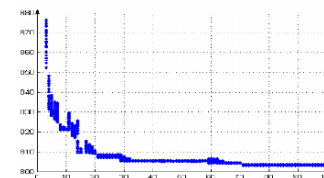
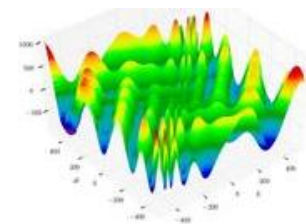
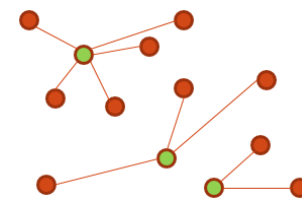
All-terrain optimization solver

For combinatorial, numerical,  
or mixed-variable optimization

Suited for tackling  
large-scale problems

Quality solutions in minutes  
without tuning

The « Swiss Army Knife » of  
mathematical optimization



free trial with support – free for academics – rental licenses  
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# P-median

Select a subset  $P$  among  $N$  points minimizing the sum of distances from each point in  $N$  to the nearest point in  $P$

```
function model() {  
  x[1..N] <- bool() ; // decisions: point i belongs to P if x[i] = 1  
  constraint sum[i in 1..N]( x[i] ) == P ; // constraint: P points selected among N  
  minDist[i in 1..N] <- min[j in 1..N]( x[j] ? Dist[i][j] : InfiniteDist ) ; // expressions: distance to the nearest point in P  
  minimize sum[i in 1..N]( minDist[i] ) ; // objective: to minimize the sum of distances  
}
```

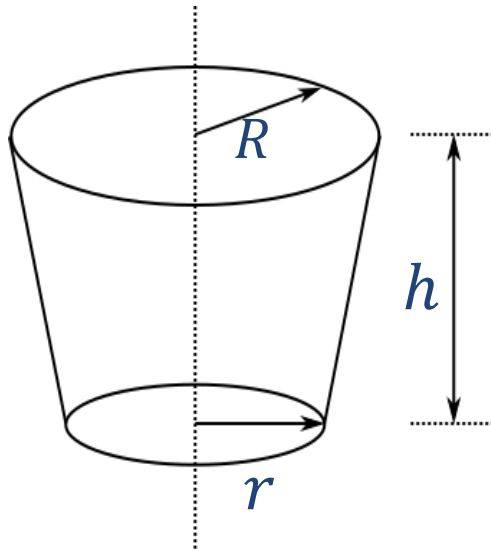
Nothing else to write: “model & run” approach

- Straightforward, natural mathematical model
- Direct resolution: no tuning



# Parametric optimization

Maximize the volume of a bucket with a given surface of metal



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```
function model() {  
  R <- float(0,1);  
  r <- float(0,1);  
  h <- float(0,1);  
  
  V <- PI * h / 3.0 * (R*R + R*r + r*r);  
  S <- PI * r * r + PI*(R+r) * sqrt(pow(R-r,2) + h*h);  
  
  constraint S <= 1;  
  maximize V;  
}
```

---

$$V = \frac{\pi h}{3} (R^2 + Rr + r^2)$$

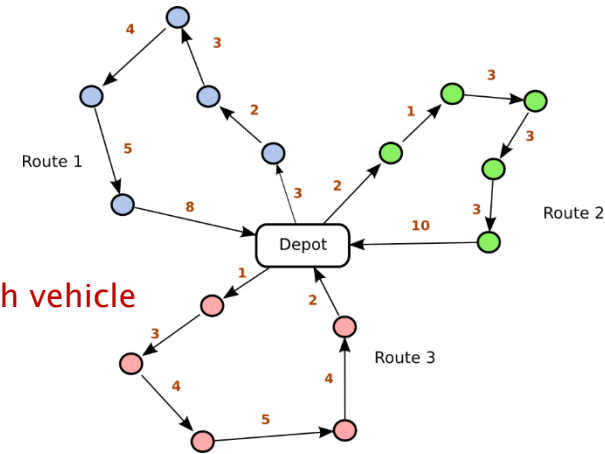
$$S = \pi r^2 + \pi(R + r)\sqrt{(R - r)^2 + h^2}$$



# Vehicle routing

Find the shortest set of routes for a fleet of  $K$  vehicles in order to deliver to a given set of  $N$  customers

```
function model() {  
  x[1..K] <- list(N); // for each vehicle, order the clients to visit  
  constraint partition( x[1..K] ); // each client is visited once  
  distances[k in 1..K] <- sum[i in 1..N-1]( dist( x[k][i-1], x[k][i] )  
    + dist( x[k][N-1], x[k][0] ); // traveled distance for each vehicle  
  minimize sum[k in 1..K]( distances[k] ); // minimize total traveled distance  
}
```



# Mathematical operators

Decisional	Arithmetical			Logical	Relational	Set-related
bool	sum	sub	prod	not	eq	count
float	min	max	abs	and	neq	indexof
int	div	mod	sqrt	or	geq	partition
list	log	exp	pow	xor	leq	disjoint
	cos	sin	tan	iif	gt	
	floor	ceil	round	array+at	lt	
	dist	scalar		piecewise		

+ operator **call** : to call an external native function which can be used to implement your own (black-box) operator



# LocalSolver

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Black-box optimization





# Black-box optimization

$$\min f(x)$$
$$x \in [x^L, x^U]$$

## Context

- Function  $f$  without analytical form (external code or library)
- Maybe be costly to evaluate (minutes or even hours)
- $f$  may be non-smooth, noisy, or even non-deterministic
- $f$  defined over continuous, integer, boolean variables
- With box constraints (bounds on variables)

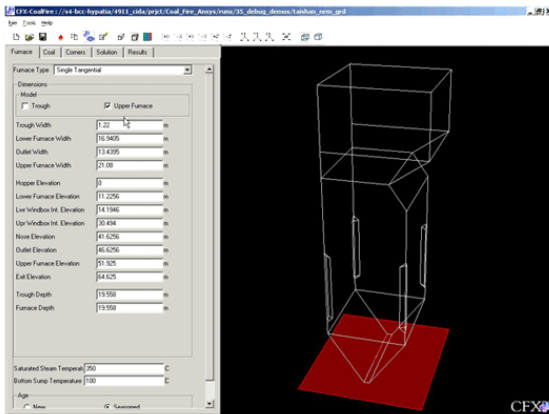
## Engineering applications

- Product or system design -> parametric optimization
- Simulation optimization



# Case study

## Designing pulverized coal boilers

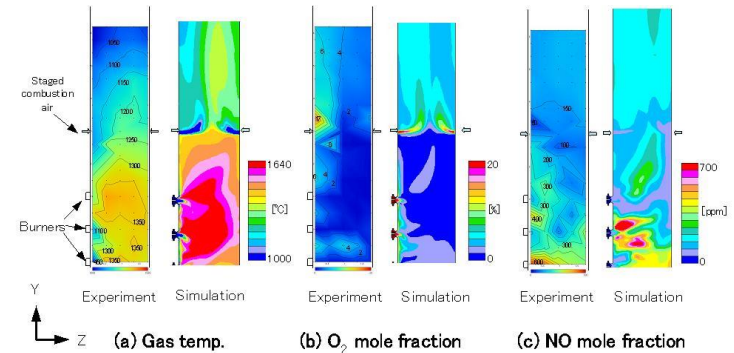


### Context

- Optimize coal injection in the boiler
- 6 criteria to optimize: 3 related to energetic performance, 3 related to pollutants
- Each call to the CFD simulator takes 12 hours

### Heterogeneous variables

- On/off: boolean variables
  - Flow rates: continuous variables
  - Angles: discrete variables
- $3 * 8 = 24$  variables to optimize



# Case study

## Designing sailboat weathervanes

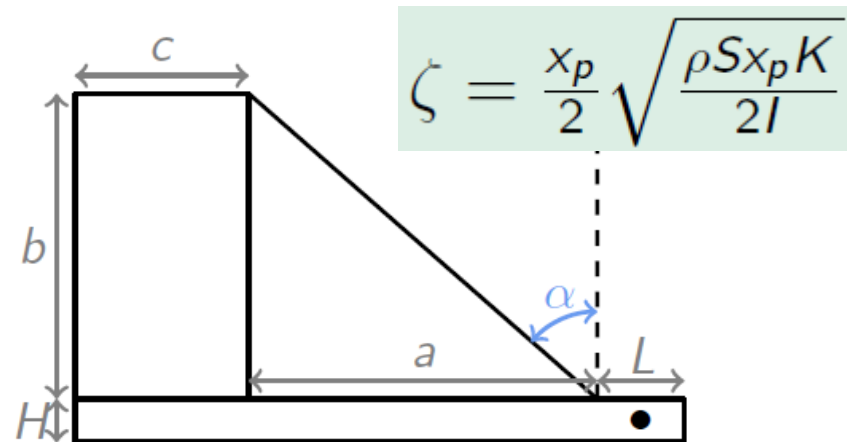


### Context

- Used to measure the wind, to drive sailboats
- No CFD simulator but complex analytical formulas to describe the physics of the weathervane

### Heterogeneous variables

- 4 continuous variables
- Precision: 0.1 millimeters
- Highly nonlinear constraints



# Resolution method

## Iterative algorithm

1. Build a model of the black-box objective
2. Use the model to find new points to evaluate
  - Minimizing the objective (Intensification)
  - Covering the search space (Diversification)
3. Call the black-box on the new point

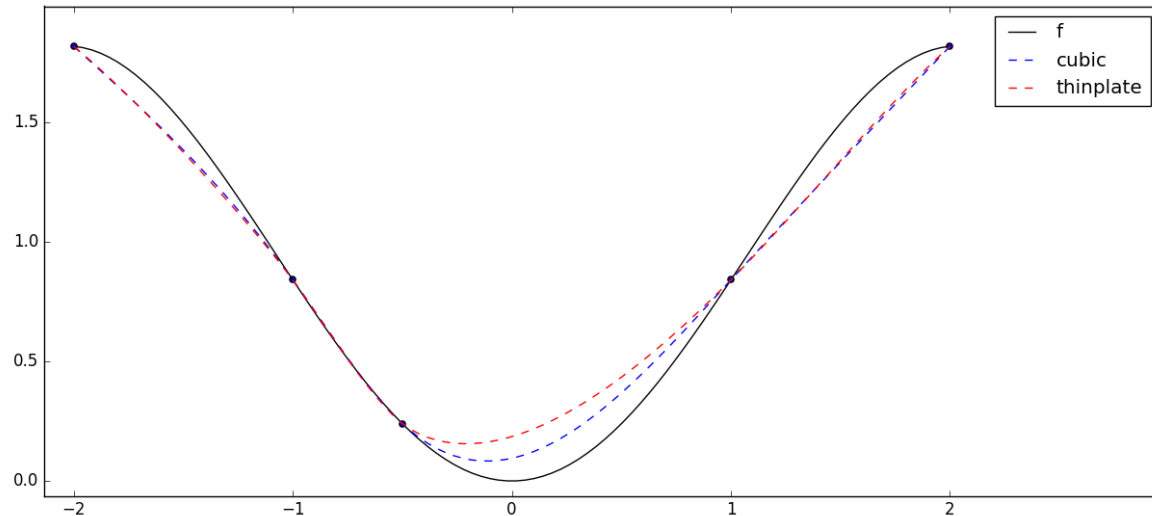


# Surrogate model

## Interpolation of evaluated points

- *Radial Basis Function*  $\phi(\|x - c\|)$  [Gutmann 01, Costa et Nannicini 14]
- Model  $m(x) = \sum_{c \in \mathcal{C}} \lambda_c \phi(\|x - c\|) + p(x)$
- Calculation of parameters  $\lambda_c$  and coefficients in  $p$ 
  - Interpolation through linear algebra direct techniques
  - Iterative resolution through LocalSolver if ill-conditioned

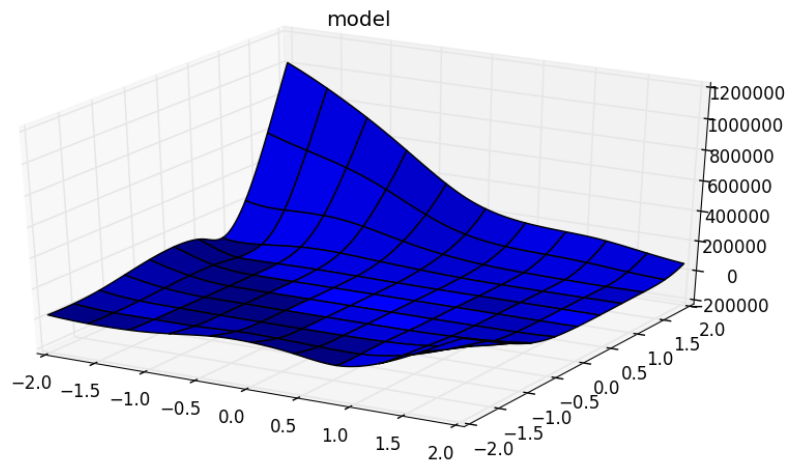
	$\phi(r)$
Cubic	$r^3$
Gaussian	$e^{-\gamma r}$
Multiquadric	$\sqrt{r^2 + \gamma^2}$
Thinplate	$r^2 \log(r)$



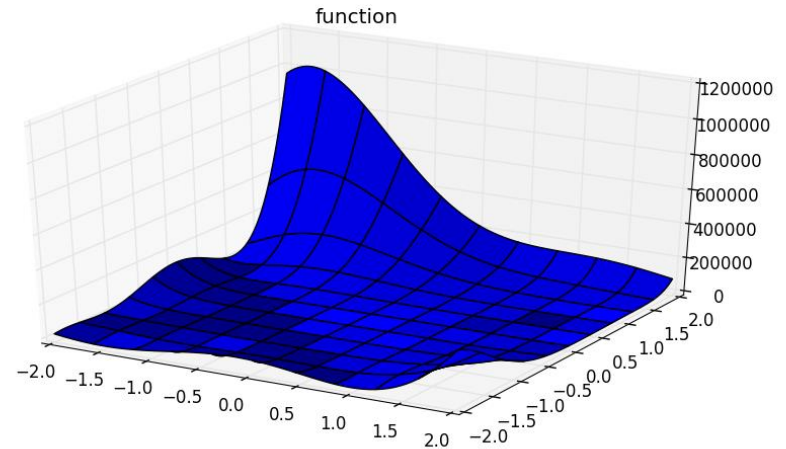
# Surrogate model

## Improved surrogate model through cross-validation

- Leave-one-out strategy to compute several models
- Select the model minimizing Root-Mean-Square deviation



RBF surrogate model



Real-world objective function



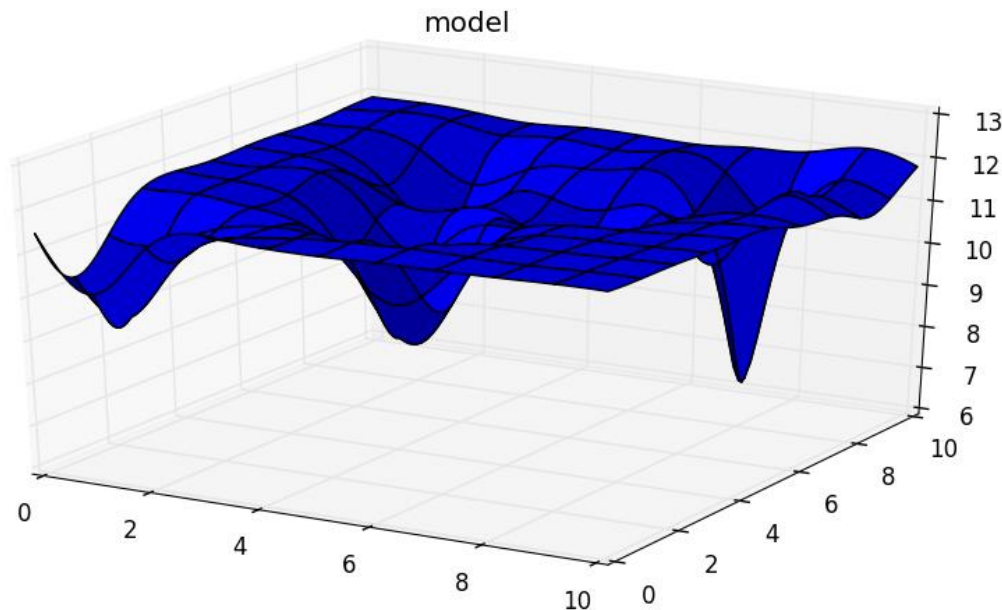
# Model-based search

## Intensification

- Search for the minimum for  $x$  over the surrogate model

$$m(x) = \sum_{c \in C} \lambda_c \phi(\|x - c\|) + p(x)$$

- Non-convex optimization over continuous and discrete variables
- Global solution approach through LocalSolver



# Model-based search

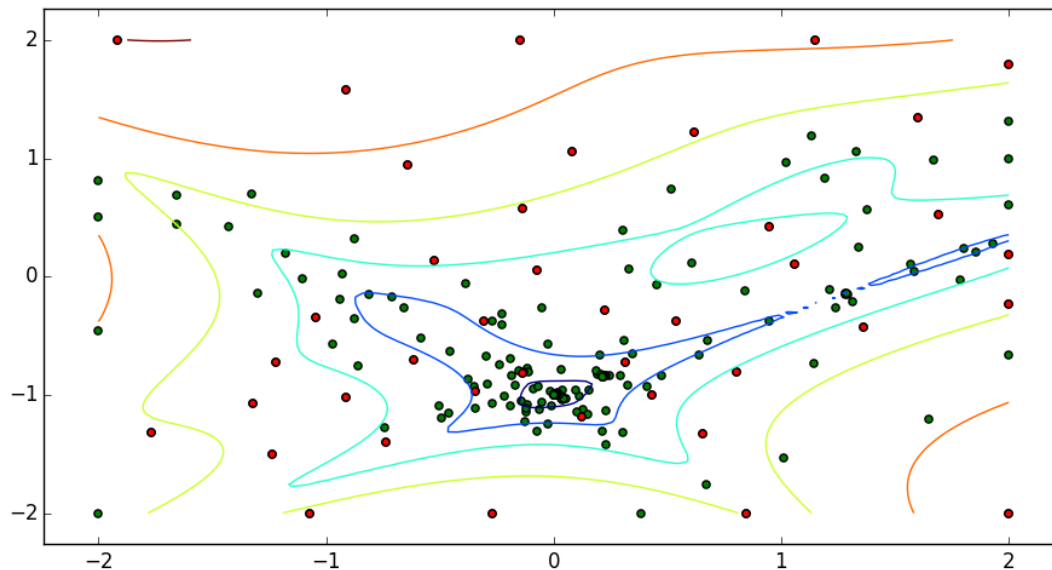
## Diversification

- Resolution of a weighted « hostile brother » problem

$$\max \left\{ \underbrace{w(x)} * \underbrace{\min_c \|x - x_c\|} \right\}$$

Penalizes « far-away » points for  $m$       Moves away from known points

- Non-convex optimization over continuous and discrete variables
- Global solution approach through LocalSolver





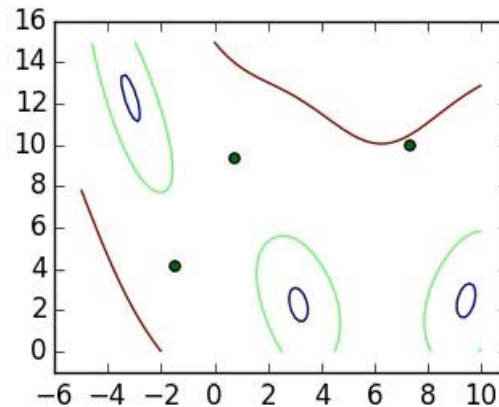
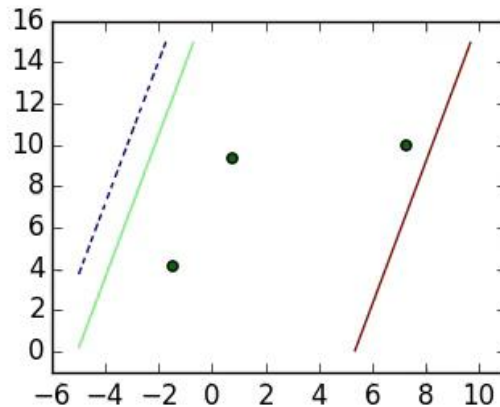
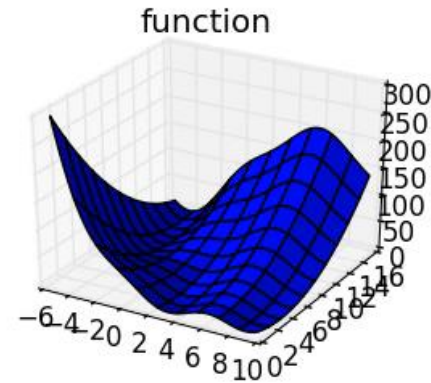
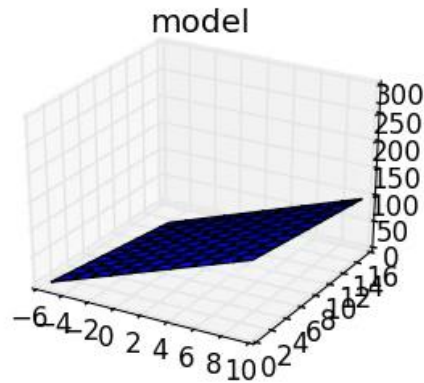
# Example

Branin  
function

$$\min \left( y - \frac{5.1}{4\pi^2}x^2 + \frac{5}{\pi}x - 6 \right)^2 + 10 * \left( 1 - \frac{1}{8\pi} \right) \cos x + 10$$

$x \in [-5, 10]$   $y \in [0, 15]$

Itr=0



# Benchmark

## Instances

- 25 instances from the most recent paper about black-box optimization
- 20 runs per instance, 150 calls max. to the black-box per run
- Numerical precision:  $1e-6$

## Results

- **LocalSolver: 310 opt. solutions found, 94 calls avg. per run**
- NOMAD (GERAD): 170 opt. solutions found



# Benchmark

Instance	LocalSolver			NOMAD	
	#sol	Avg. Eval	Error (%)	#sol	Error (%)
branin	20	23	0,0	20	0,0
camel	20	26	0,0	19	4,0
ex_4_1_1	20	11	0,0	20	0,0
ex_4_1_2	20	51	0,0	20	0,0
ex_8_1_1	20	10	0,0	19	2,5
ex_8_1_4	20	44	0,0	0	341,5
gear	20	34	0,0	0	388,0
goldsteinprice	18	122	0,0	16	450,0
hartman3	8	130	0,0	15	9,4
hartman6	8	121	5,1	0	5,7
least	0	150	204,7	0	129,0
nvs04	20	70	194,4	4	9997,0
nvs06	16	127	13,3	9	8,7
nvs09	20	15	0,0	16	1,2
nvs16	8	138	0,0	9	885,0
perm0_8	0	150	147,2	0	412,0
perm_6	0	150	44134,7	0	311032,0
rbrock	20	83	10,8	0	43,2
schoen_10_1	4	145	28,8	0	119,5
schoen_10_2	0	150	1,6	0	115,7
schoen_6_1	18	101	1,8	0	51,5
schoen_6_2	10	120	32,7	0	54,2
shekel10	8	118	60,1	0	56,9
shekel5	6	127	51,7	1	46,1
shekel7	6	127	47,0	2	47,9
	310			170	





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